## INFRARED CALIBRATION Menzel September 1993

For cloud applications, radiances must be RMS accurate to better than

.25 mW/m2/ster/cm-1 (longwave)

.004 mW/m2/ster/cm-1 (shortwave)

Procedure

assume linear radiometer (radiance linear wrt volts measured)

 $\mathbf{R} = \mathbf{m} \mathbf{V} + \mathbf{b}$ 

expose radiometer to two known sources to set line

space	Rz = m Vz + b
bb	Rbb = m Vbb + b

repeat often so that temperature changes in foreoptics are tracked by Vz

correct for non-linearity by determining q before launch

 $R = q V^2 + m V + b$ 

or in another form

R = m V (1 + q V) + b

determine q for several baseplate temperatures

Examples from NOAA polar orbiters

Implementation





















IMPLEMENTATION

1. CONVERT THERMISTOR READING

(EXT BB, FOREOPTICS) TO TEMPERATURE USING

 $T = d_{1} + d_{1} \times + d_{2} \times^{2} + d_{3} \times^{3}$ .

- NEED: PRE-LAUNCH DETERMINATION OF THERMISTOR PERFORMANCE THROUGH RANGE OF EXPECTED IN-FLIGHT BASEPLATE TEMPERATURES (CUBIC FIT REQUIRES MORE THAN FOUR TEMPERATURE PLATEAUS)
- 2. CALCULATE RADIANCE FOR EACH SPECTRAL BAND

$$R(T) = \int SR(v) B(v,T) dv$$

WHERE SR IS THE NORMALIZED SPECTRAL RESPONSE. USE CUBIC FIT

$$R(T) = \beta_0 + \beta_1 T + \beta_2 T^2 + \beta_3 T^3$$
.

NEED: PRE-LAUNCH DETERMINATION OF FILTER RESPONSES.

3. CORRECT VOLTAGE READING FOR NONLINEARITY APPROPRIATE TO BASEPLATE TEMPERATURE

$$V' = V + f(T_{bp})V^{2} + f'(T_{bp})V^{3}$$

- NEED: PRE-LAUNCH DETERMINATION OF NONLINEARITY THROUGH RANGE OF EXPECTED INFLIGHT BASEPLATE TEMPERATURES (AT FIVE PLATEAUS)
- 4. DETERMINE TARGET RADIANCE

$$R = R_{BB} (V' - V'_{2}) / (V'_{BB} - V'_{2})$$

NEED: SPACE AND BB VIEW AS OFTEN AS POSSIBLE; IN BETWEEN EXTRAPO-LATE CALIBRATION BY TRACKING FOREOPTICS TEMPERATURE(S).

## REGISTRATION

- A. FOR SOUNDING OVER A GIVEN AREA, THE MULTISPECTRAL OBSERVATIONS MUST ALL COME FROM THE SAME AREA.
- B. MISREGISTRATION EFFECTS THE CLOUD CLEARING ALGORITHM,



 $\Delta R \equiv ERROR \equiv DIFFERENCE BETWEEN RADIANCES OF ACTUAL AND EXPECTED FOVS$ 

- $= (x/225)(N_{CLOUD} N_{CLEAR})$
- 2. Example for GOES-I channel 5 (750 cm<sup>-1</sup>) viewing  $T_{cloud} = 220$ °K and  $T_{sec} = 280$ °K, maximum misregistration error is

 $\Delta R = (10/225)(37.5 - 108.7) = -3.2 \text{ MW/STER/M}^{-1}$ 

(SPECIFIED SINGLE SAMPLE NOISE = .44 MW/STER/M<sup>2</sup>/CM<sup>-1</sup>)

Data needed to define IR MODIS calibration algorithm and its relative and absolute accuracy. Menzel/Kaufman

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- Spectral response for each IR detector/spectral channel combination

   a) system spectral response function (best estimate)
- 2) Calibration tested for several instrument thermal configurations

  a) stabilize to isothermal temperatures in foreoptics,
  b) simulate "inflight" temperature gradients
  (orbit low in earth shadow, orbit high in daylight)
  c) isolate selected foreoptics components with a high temperature (use clip on heater).
- 3) Stray radiation must be characterized as a function of view angle
  - a) background when viewing blackbody
  - b) background when viewing space
  - c) background when viewing earth target
- 4) Non linear response and repeatability must be characterized
  - a) at least ten external target temperatures (more temperatures should be pursued)
  - b) repeated measurements at different times
  - c) record should include
    - \* time of test
    - \* thermistor readings of all foreoptics components
    - \* thermistor readings of internal bb
    - \* detector counts for target, int bb, and space (mean and std)
- 5) Data will be used to calculate R=a+bC+qC2
  - a) for each thermal configuration
  - b) for each detector
  - c) for each spectral channel.

and to characterize nonlinearity of the calibration equation as a function of instrument temperature (q(T)).

6) Half will be used to specify algorithm, half to determine cal alg performance.